Problems, and How Computer Scientists Solve Them

Manas Thakur PACE Lab, IIT Madras



Content Credits

- Introduction to Automata Theory, Languages, and Computation, 3rd edition. Hopcroft et al.
- Introduction to the Theory of Computation, 2nd edition. Michael Sipser.
- *Algorithms*, TMH edition. Dasgupta et al.
- https://en.wikipedia.org
- https://images.google.com



Outline

- Computation models
- Solvability
- Complexity
- Coping with difficulties



Ways to begin a talk: The Overdone Overview



A Simple Problem

• Design a machine to determine whether a given program P1 prints "Hello World!".

```
int main() {
    printf("Hello World!");
    return 0;
}
```



A Simple Problem (Cont.)

```
int main() {
    int n, total, x, y, z;
    scanf("%d", &n);
    total = 3;
    while (1) {
        for (x=1; x<=total-2; ++x) {</pre>
             for (y=1; y<=total-x-1; ++y) {</pre>
                  z = total - x - y;
                  if (exp(x,n)+exp(y,n) == exp(z,n)) {
                      printf("Hello World!");
                  }
             }
         }
         ++total;
    }
    return 0;
```

```
int exp(int i, int n) {
    int ans, j;
    ans = 1;
    for (j=1; j<=n; ++j) {
        ans *= i;
    }
    return ans;
}</pre>
```

}



Expressing problems as language-membership tests

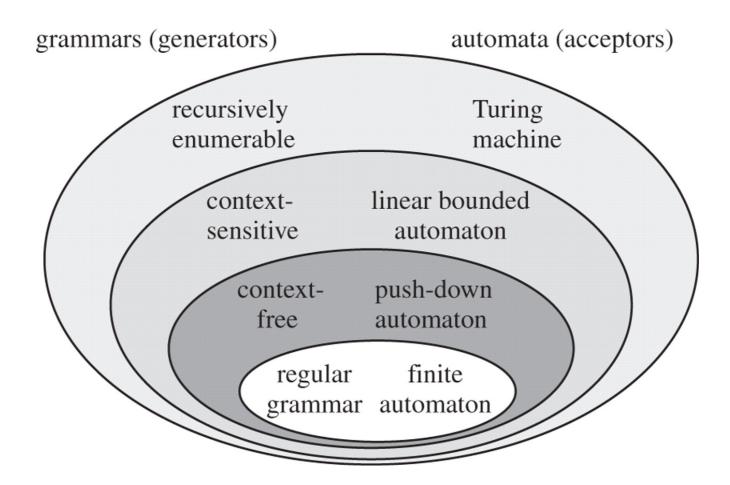
- **Step 1:** Represent problem instances as *strings* over a finite alphabet.
 - Our program P1 is essentially a string of characters.
- **Step 2:** Design a machine M1 that accepts *valid* strings.
 - Outputs *yes*, if P1 prints "Hello World!".
 - Outputs *no*, if P1 does not print "Hello World!".
- The language accepted by M1 is:

L(M1) = { w | w is a program that prints "Hello World!" }

 If M1 always terminates and prints yes or no, it decides P1; else it recognizes P1.

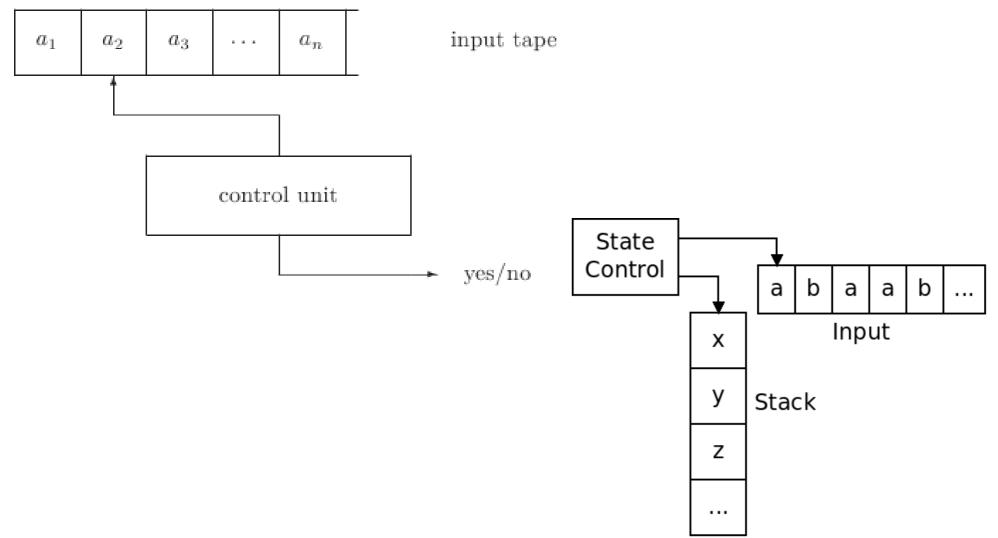


The Chomsky Hierarchy of Languages





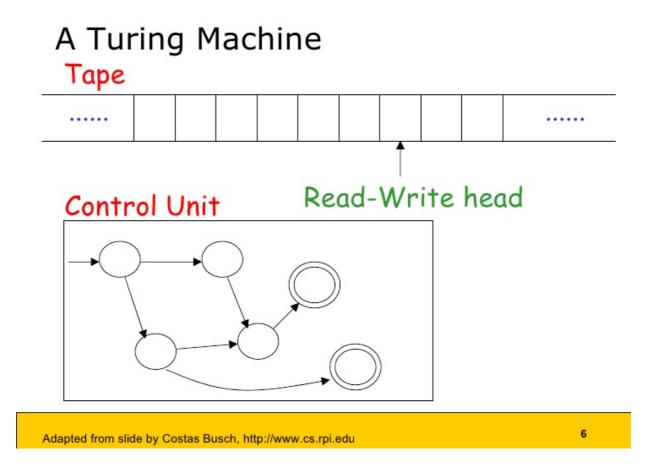
DFA and PDA: A Quick Recap





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Turing Machines





Where are we?

- Computation models
- Solvability
- Complexity



• Coping with NP-Completeness



An "undecidable" problem

- Given a TM *M*, and an input *w*, does *M* halt on *w*?
- Step 1:

 $L(M) = \{ \langle M, w \rangle \mid M \text{ is a TM that halts on } w \}$

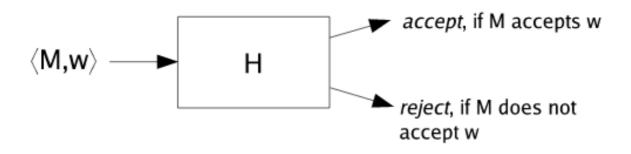
• Step 2:





Our First Undecidability Proof

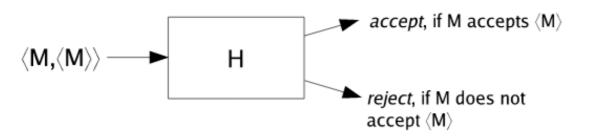
- Prove that A_{TM} = { <M,w> | M is a TM that accepts w } is undecidable.
- Assume that A_{TM} is decidable by the following TM H:



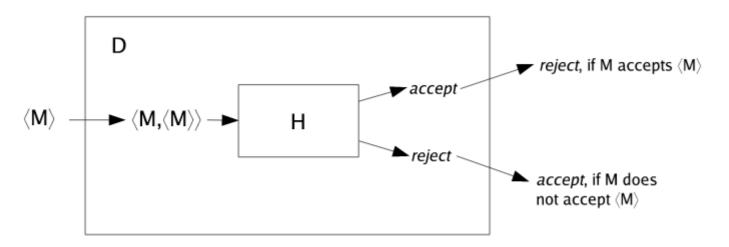


Our First Undecidability Proof

• Give the string representation of M as input to H:



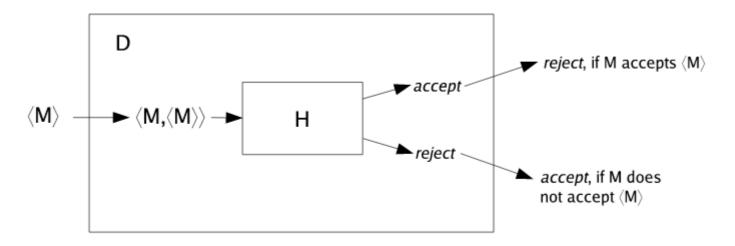
• Construct another TM D as follows:





Our First Undecidability Proof

• What does D do on <D> as input?

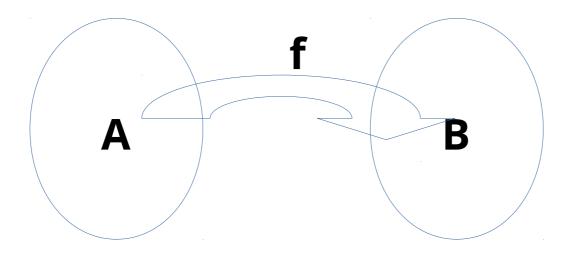


- *D* accepts <*D*> if *D* does not accept <*D*>, and vice-versa.
- Contradiction!
- Hence, H does not exist. Thus, A_{TM} is undecidable!! :-)



Reducibility

• Reduce Problem A to Problem B.



- If B is decidable, so is A.
- If A is undecidable, so is B.

~(p implies q) == ~q implies ~p



Back to the Halting Problem

- L(M) = { <M,w> | M is a TM that halts on w }
- Assume M_H decides L(M).
- Reduce A_{TM} to M_{H} :
 - Run M_H on <M,w>.
 - If M_H rejects (i.e., M does not halt on *w*), then *reject*.
 - If M_{H} accepts, then simulate M on *w* (guaranteed to stop).

 $A_{TM} = \{ \langle M, w \rangle \mid M \text{ is a TM that accepts } w \}$

- *Accept* if M accepts *w*; *reject* if M rejects *w*.
- Thus, if M_{H} always halts (assumed above), then A_{TM} is decidable.
- Contradiction!
- Note that *M_H* is Turing-recognizable, though.

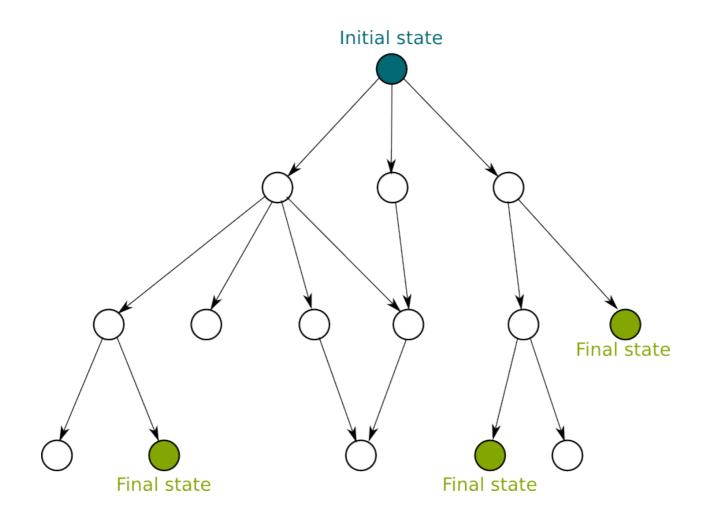


Turing Machines and Algorithms

- **Church-Turing Thesis:** Every algorithm can be realized as a Turing Machine.
- A multitape-TM is equivalent to a single-tape TM.
- A TM can simulate a computer.
- A computer with an *infinite tape* can simulate a TM.
- Turing Machines are more powerful than modern day computers!!
- What about Nondeterministic Turing Machines?



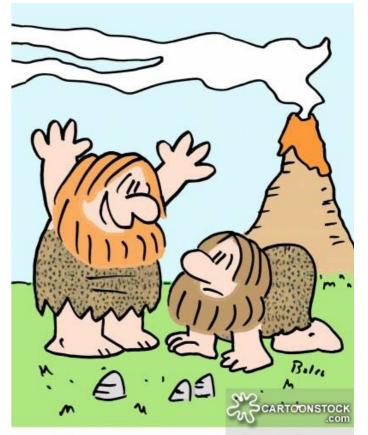
Non-determinism: The Power of Guessing





A Shift

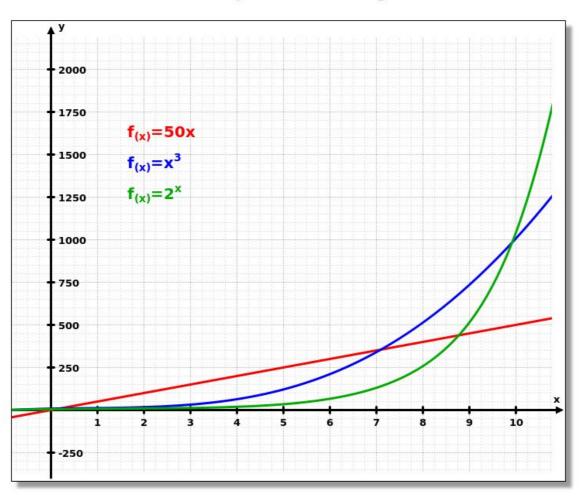
- Computation models
- Solvability
- Complexity
- Coping with NP-Completeness



"Man, you've got to try this 'walking upright' stuff! — it's like a total paradigm shift!"



Can a problem be solved in "good-enough" time?



Linear vs Polynomial vs Exponential

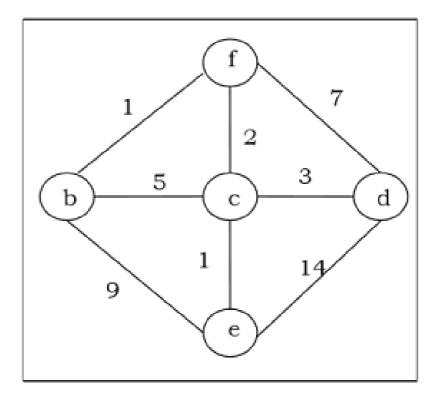


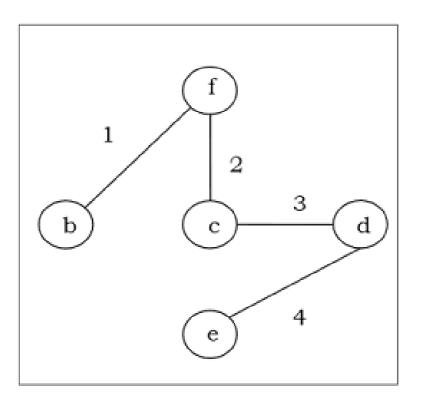
The P class of problems

- Problems that can be solved in polynomial time by a Deterministic Turing Machine
- All practical problems that we write algorithms for
- Example: Minimum Spanning Tree



The Minimum Spanning Tree Problem







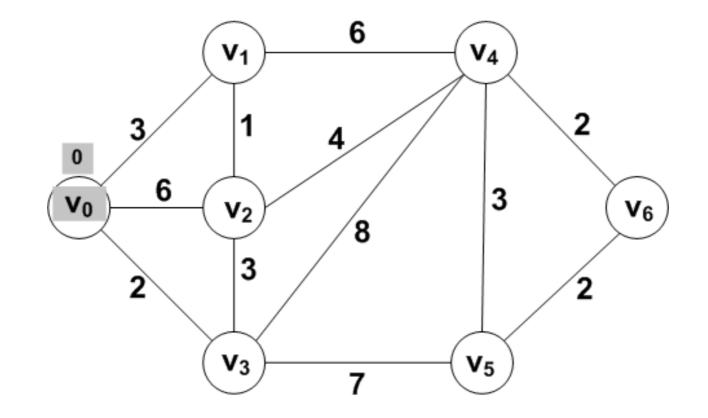
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The NP class of problems

- Problems that can be solved in polynomial time by a Nondeterministic Turing Machine
 - A given solution can be *checked* in polynomial time by a Deterministic Turing Machine
- Even though the power of an NTM is equivalent to that of a DTM, the time requirements of NP may not be in the "good-enough" zone
- Example: Travelling Salesman Problem (decision version)



The Travelling Salesman Problem





Is *P* = *NP*?

- A problem Q is *NP-Complete* if:
 - Q is in NP
 - All problems in *NP* can be reduced (in polynomial time) to Q
- A problem R is *NP-Hard* if:
 - All problems in *NP* can be reduced (in polynomial time) to R
 - It's not known whether R is in *NP*
- Thus, if even a single NP-Complete problem can be solved by an algorithm in polynomial time, then P = NP.
- It seems that P != NP; however, there is no proof yet!

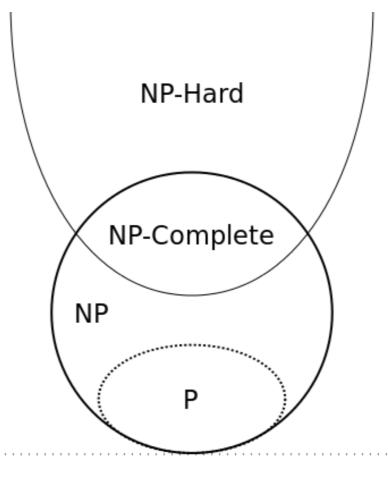


Some popular problems

- NP-Complete:
 - TSP
 - SAT
 - Subset sum
 - Vertex cover
 - Graph coloring
 - Decision version of TSP
- NP-Hard but not NP-Complete:
 - The Halting Problem (undecidable)
 - General TSP

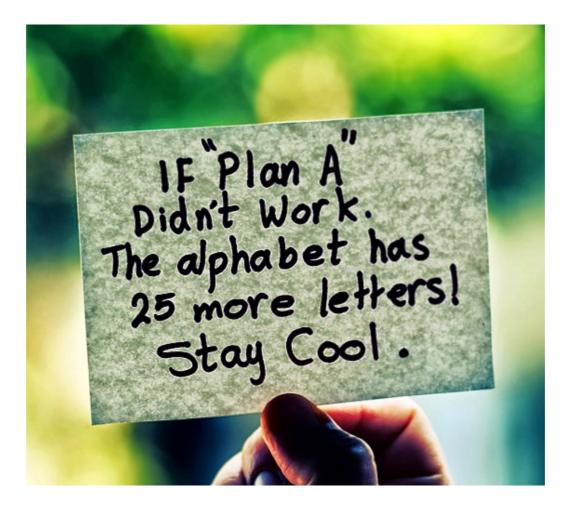


A conclusive picture:





So do we give up?

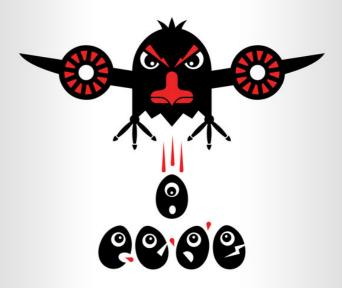




Never surrender!

- Computation models
- Solvability
- Complexity
- Coping with NP-Completeness

WE SHALL NEVER SURRENDER!



We shall fight with growing confidence and growing strength in the air. We shall defend our nests whatever the cost may be; we shall fight on tree tops, landing branches, in fields and on the hills. We shall never surrender!



Special Cases

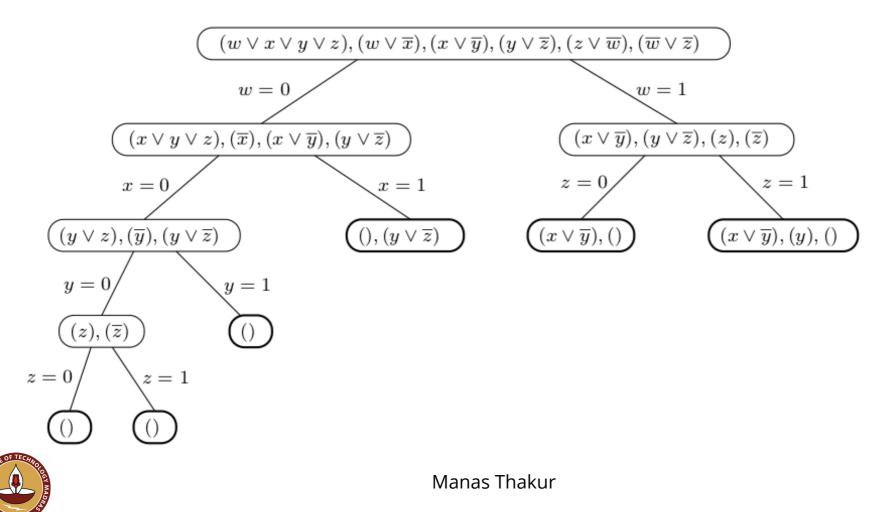
- SAT is *NP-Complete*.
- 2-SAT is in *P*.

- Vertex cover problem is *NP-Complete*.
- Vertex cover problem for bipartite graphs is in *P*.



Intelligent Backtracking

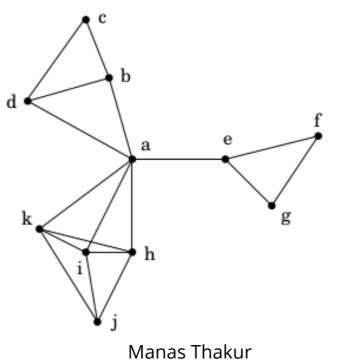
- Useful for exhaustive space-search problems
- Consider the SAT instance:



Approximation

- Obtain a near-optimal solution
- Consider the following problem:

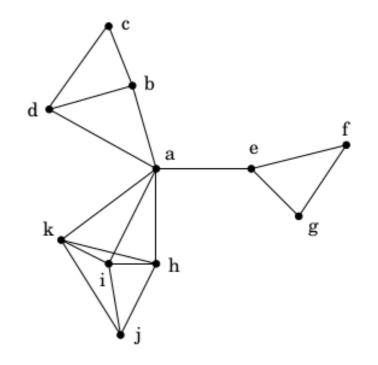
There are 11 towns. According to a government policy, each hospital can cover 30 miles of distance around it. Find the optimal number of hospitals that need to be opened.





Approximation (Cont.)

- Can be reduced to the Set Cover problem:
 - Input: A set of elements
 - Output: A selection of S_i whose union is B
 - Cost: Number of sets picked
- *Greedy algorithm:* At each step, pick the set S_i with the largest number of uncovered elements
 - {a, c, j, f} or {a, c, j, g}
- *Optimal:* {b, e, i}
- It can be proved that if the optimal set has k elements, the Greedy algorithm generates at max k.lnn sets.





So how do YOU solve problems?

- Ask others for a solution
- Think, re-think, and think more
- Find a best-attempt solution
- Simplify the problem
- Try to generalize the solution
- Prove it unsolvable!



How do *Computer Scientists* solve problems?

- Ask others for a solution
- Think, re-think, and think more
- Find a best-attempt solution
- Simplify the problem
- Try to generalize the solution
- Prove it unsolvable!

- Reduction
- Different algorithms
- Approximation
- Special cases
- Other cases?
- Prove it NP-Complete!



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www.cse.iitm.ac.in/~manas





github.com/manasthakur gist.github.com/manasthakur

manasthakur17@gmail.com





manasthakur.wordpress.com

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